

# ANALYSIS OF SPECTRUM SHARING FOR UNMANNED AERIAL SYSTEMS

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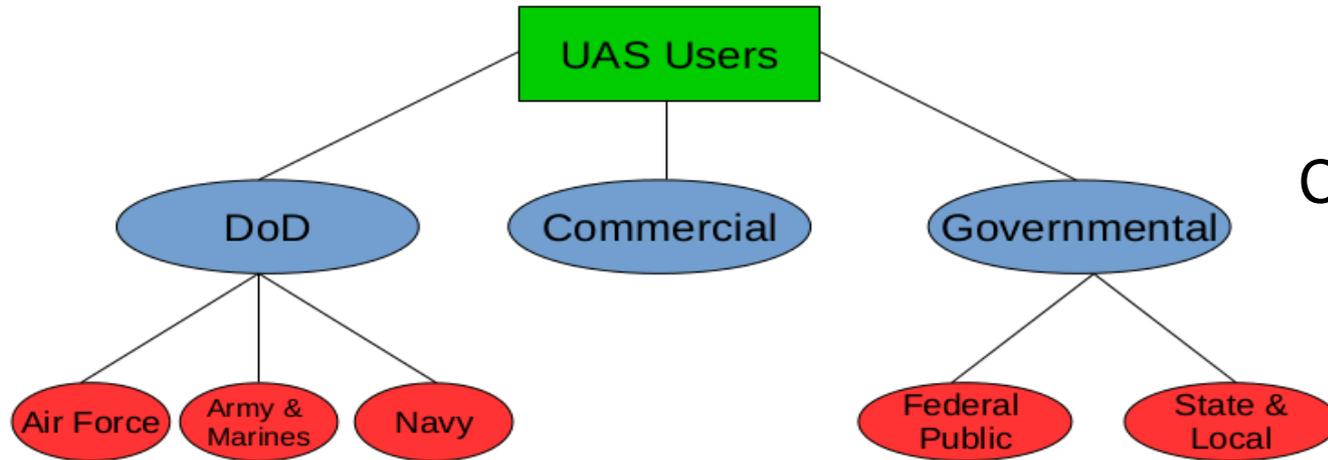
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# Introduction

- Unmanned aircraft system (UAS) is the **aggregation** of multiple systems:
  - Unmanned aircraft subsystem
  - Ground control station (GCS) subsystem
  - ATC subsystem
  - Sense & Avoid subsystem
  - Payload subsystem (e.g. video camera, etc.).
  
- The physical aircraft is the unmanned aerial vehicle (UAV) or, simply, unmanned aircraft (UA)
  
- **Well-developed** UAV technology
- Significantly **lower costs** than that of traditional manned aircraft systems [1]

# Projected and Current Applications



Categorization of UAS Users

## Application Examples

Role	Commercial	Role	Governmental	
			Federal	State & Local
<b>Media</b>	<ul style="list-style-type: none"> <li>- Event filming</li> <li>- Aerial photography</li> <li>- Information services</li> </ul>	<b>Science</b>	<i>Earth &amp; Environment</i>	
<b>Transport</b>	<ul style="list-style-type: none"> <li>- Cargo planes</li> </ul>		<ul style="list-style-type: none"> <li>- Pollution and land monitoring</li> <li>- Meteorological services</li> </ul>	
<b>Monitoring</b>	<i>Security</i> <ul style="list-style-type: none"> <li>- Pipeline</li> </ul> <i>Inspection</i> <ul style="list-style-type: none"> <li>- Power and rail line</li> </ul>		<ul style="list-style-type: none"> <li>- Biological services</li> <li>- Research</li> </ul>	
<b>Communications</b>	<ul style="list-style-type: none"> <li>- Relay</li> <li>- Remote sensing</li> <li>- Disaster eNBs</li> </ul>	<b>Security</b>	<ul style="list-style-type: none"> <li>- Coast line</li> <li>- Border patrol</li> <li>- Anti-terror fight</li> <li>- Search &amp; Rescue</li> <li>- Disaster and catastrophe management</li> </ul>	<ul style="list-style-type: none"> <li>- Police support</li> <li>- Fire fighting</li> <li>- Traffic spotting</li> <li>- Forest fire avoidance</li> </ul>
<b>Agriculture</b>	<ul style="list-style-type: none"> <li>- Crop spraying/dusting</li> <li>- Forestry operations</li> </ul>		<b>Humanitarian Support</b>	<ul style="list-style-type: none"> <li>- Famine relief</li> <li>- Medical support</li> <li>- Emergency relief</li> </ul>

# Classification of UAVs [2]

- Useful UAV Classification are mean takeoff weight (MTOW) based

Name	MTOW [kg]	Operating Altitude [m]	Mission Radius [km]	UAV Examples
Nano	< 0.5	< 120	1.6	Hummingbird
Micro	0.5 – 2	< 915	< 8	Raven A/B
Small	2 – 25	< 3,050	< 40	T-Hawk
Ultralight Aircraft	25 – 115	< 4,570	< 120	Integrator
Light Sport Aircraft	115 – 600	< 5,500	< 160	Shadow
Small Aircraft	600 – 5,670	< 7,620	< 320	Reaper
Medium Aircraft	5,670 – 18,600	< 30,500	TBD	Global Hawk
Large Aircraft	18,600 – 136,000	?	?	Pegasus



Nano UAV:  
Hummingbird



Micro UAV:  
Raven A/B



Small UAV:  
RQ-16A T-Hawk

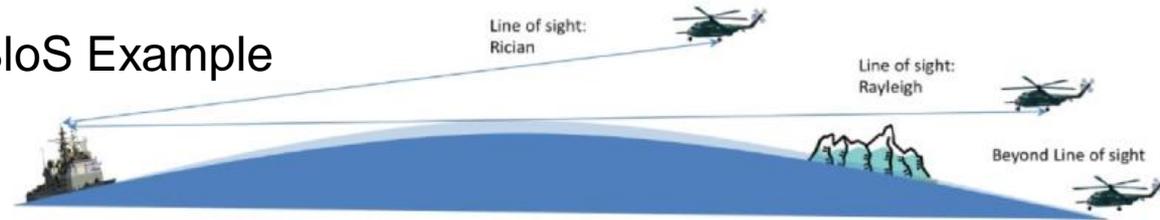


Small UAV:  
RQ-16A T-Hawk

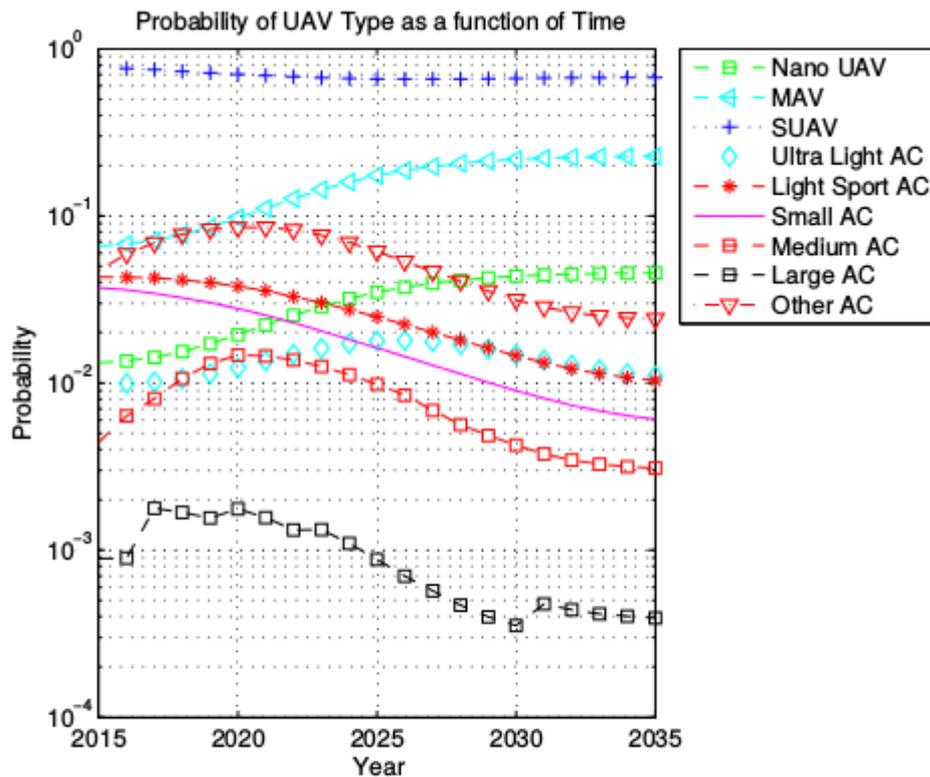
# Projected Relative UAV Quantities

- Around 22% and 67% will be of type MAV and SUAV by 2035
- SUAV and MAV communication typically LoS radio communication [3] (and not BLoS)
- BLoS is the **indirect** radio communication between the UA and a UACS using **satellite communication services**

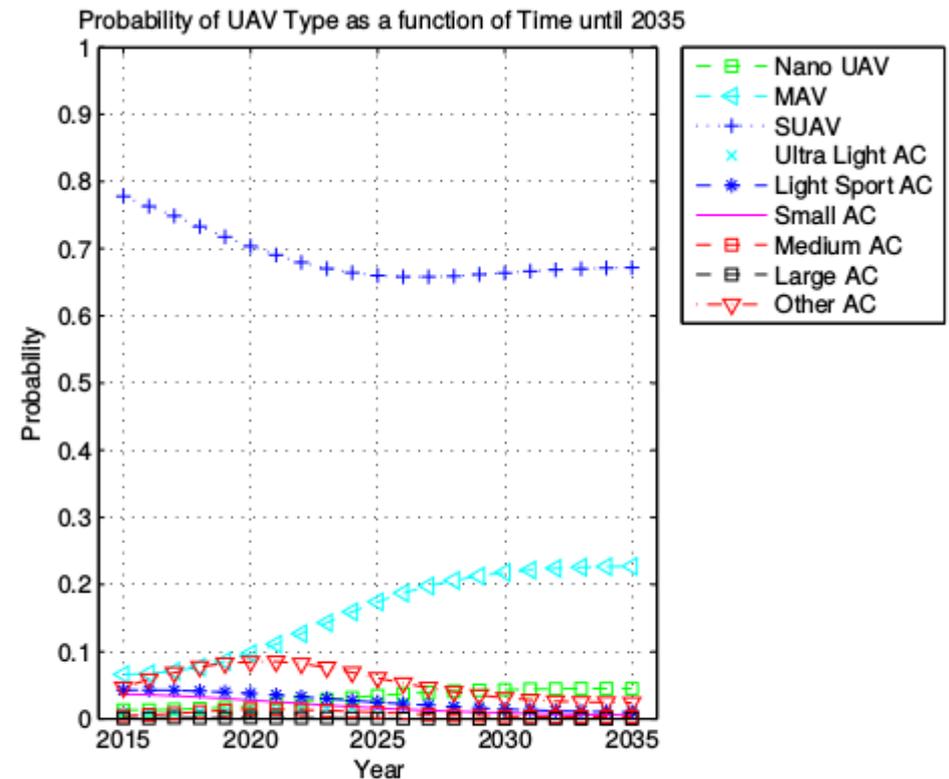
## LoS and BloS Example



## PMF of UAV Quantities

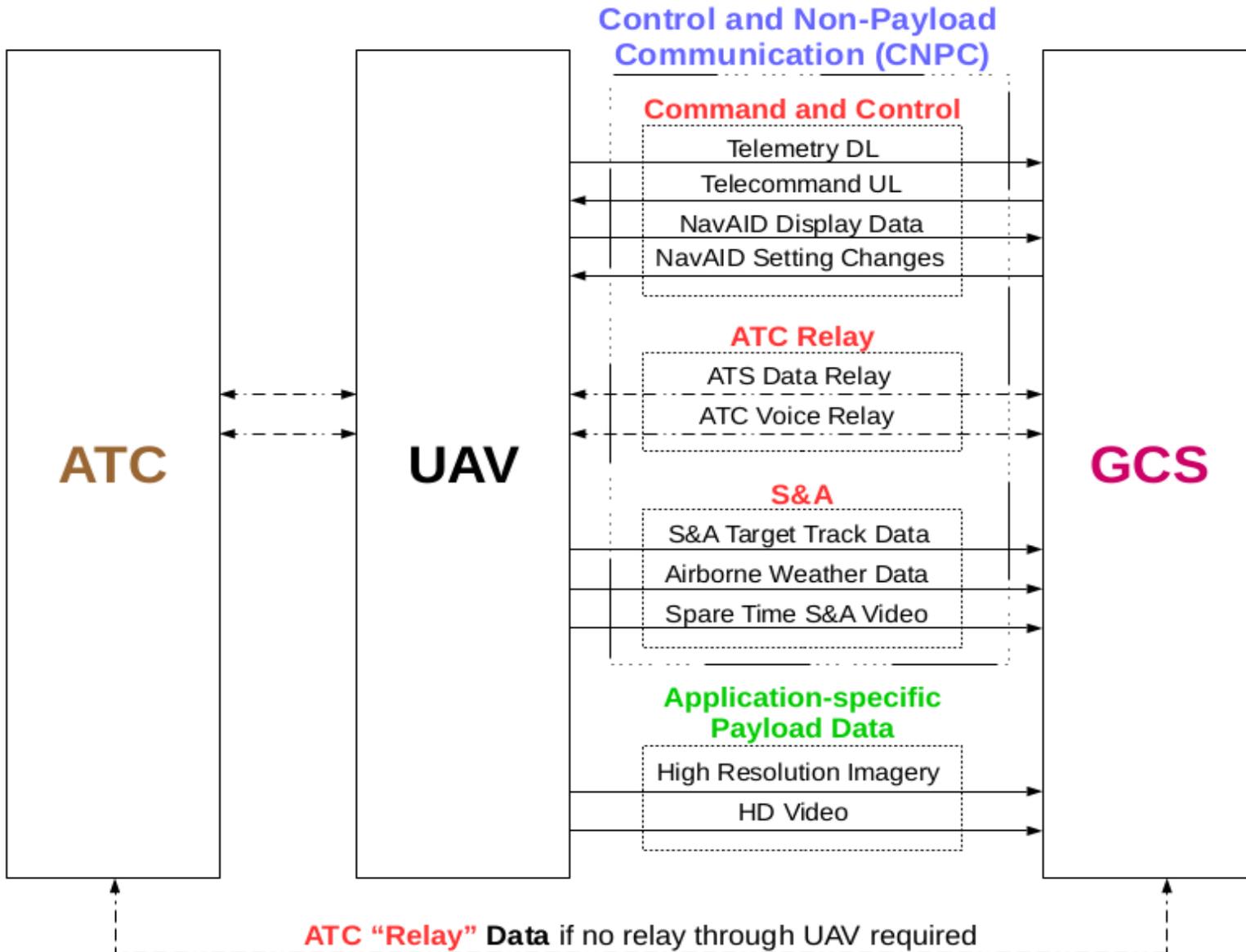


(a) Log-scaled PMF of UAV types



(b) Linear-scaled PMF of UAV types

# Control and Non-payload Communication (CNPC) and Payload Links



# Computed Spectral Requirement

- Bandwidth Requirement for any link:  $W = K \cdot B \cdot M \cdot R / (U \cdot E)$
- Computation is based on Methodology I of ITU-R [4]
- Only 34 MHz of spectrum for LoS CNPC is intended to be allocated
- Increase of Spectral Efficiency to 1.45 bps/Hz

	<b>C2</b>	<b>ATC Relay</b>	<b>S&amp;A Low Latency</b>	<b>S&amp;A Medium Latency</b>	<b>Video/Weather Radar</b>
$R$	2	2	2	1.5	1
$U$	0.5	1	0.5	0.75	1
$E$ [bps/Hz]	0.75				
Ratio $R/(U \cdot E)$	5.33	2.66	5.33	2.66	1.33

<b>Cell Type</b>	<b>M</b>	<b>K</b>	<b>B · R / (U · E) [kHz]</b>			<b>Spectrum Need [MHz]</b>		
			<b>DL</b>	<b>UL</b>	<b>Overall</b>	<b>DL</b>	<b>UL</b>	<b>Overall</b>
Surface	3	1	451.2	36.1	487.3	1.35	0.11	1.46
A	5	7	451.2	36.1	487.3	15.79	1.26	17.05
B	70	4	102.5	22.9	125.4	28.69	6.42	35.10
C	24	3	102.5	22.9	125.4	7.38	1.65	9.03
D	8	3	102.5	22.9	125.4	2.46	0.55	3.01
<b>Total</b>						55.67 <sup>21</sup>	9.99 <sup>19</sup>	65.65 <sup>22</sup>

# Air-to-Ground Propagation

- Cell Planning in Spectrum Computation is utilizing radio horizon as link range
- For LAPs high shadowing effect at low elevation angles

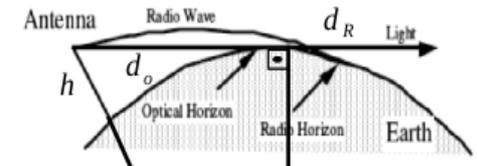
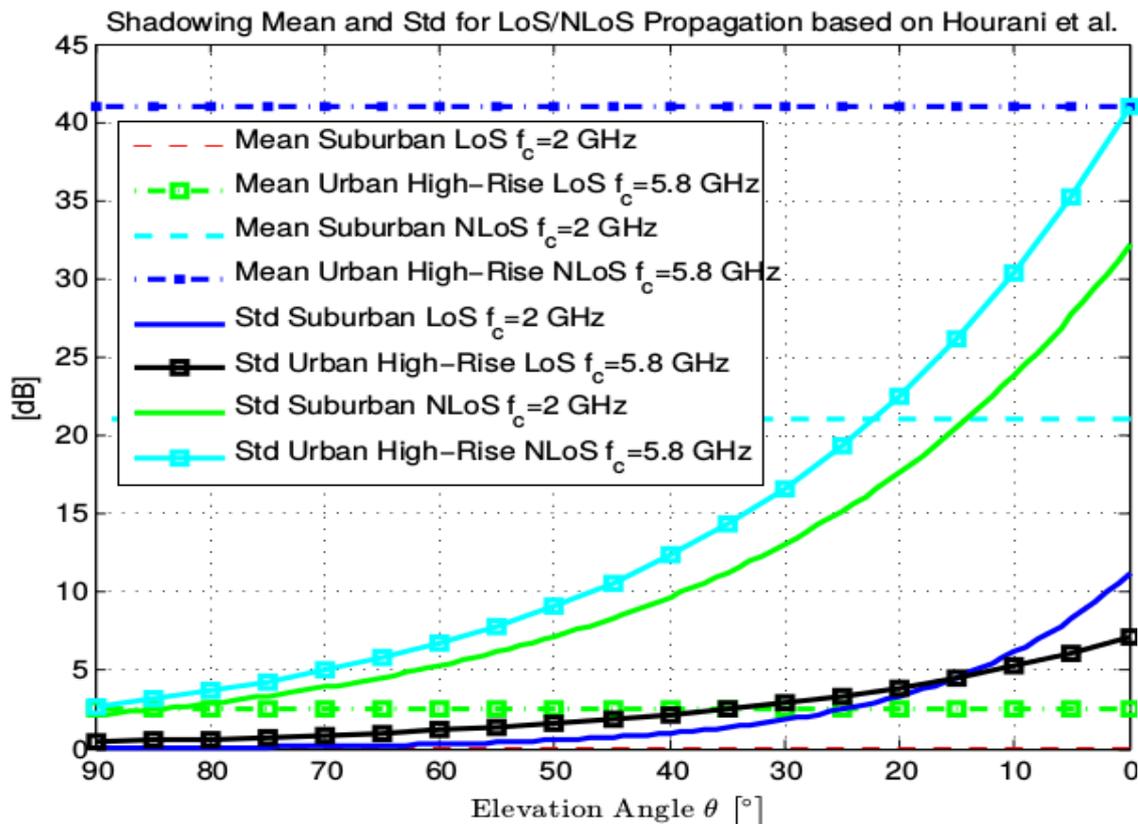


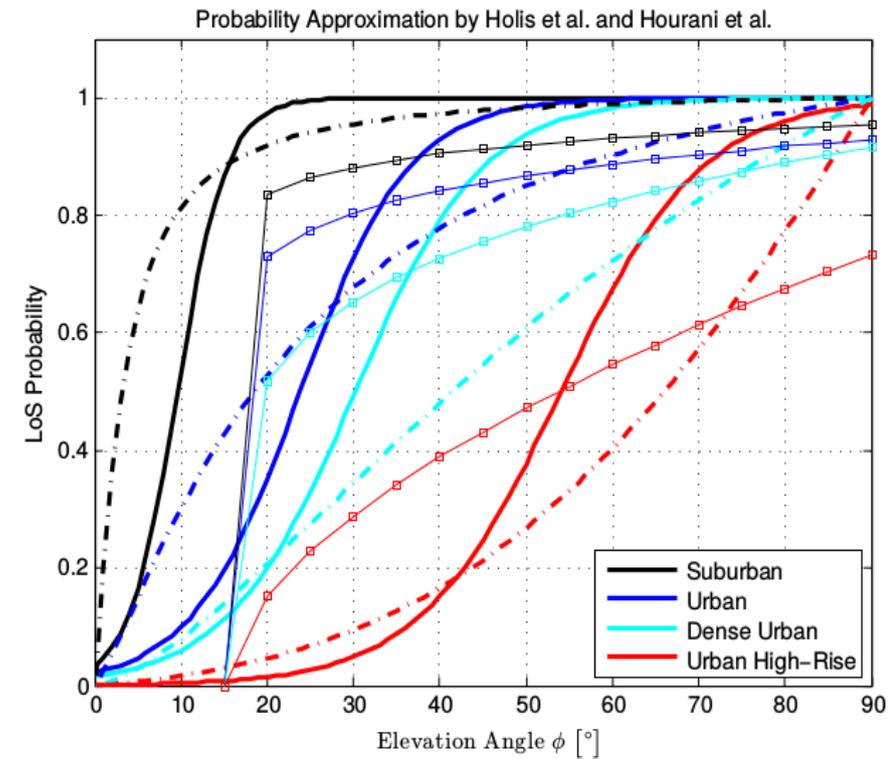
Illustration of Radio Horizon

$R \approx 6,371 \text{ km}$

Shadowing of LAP [5]

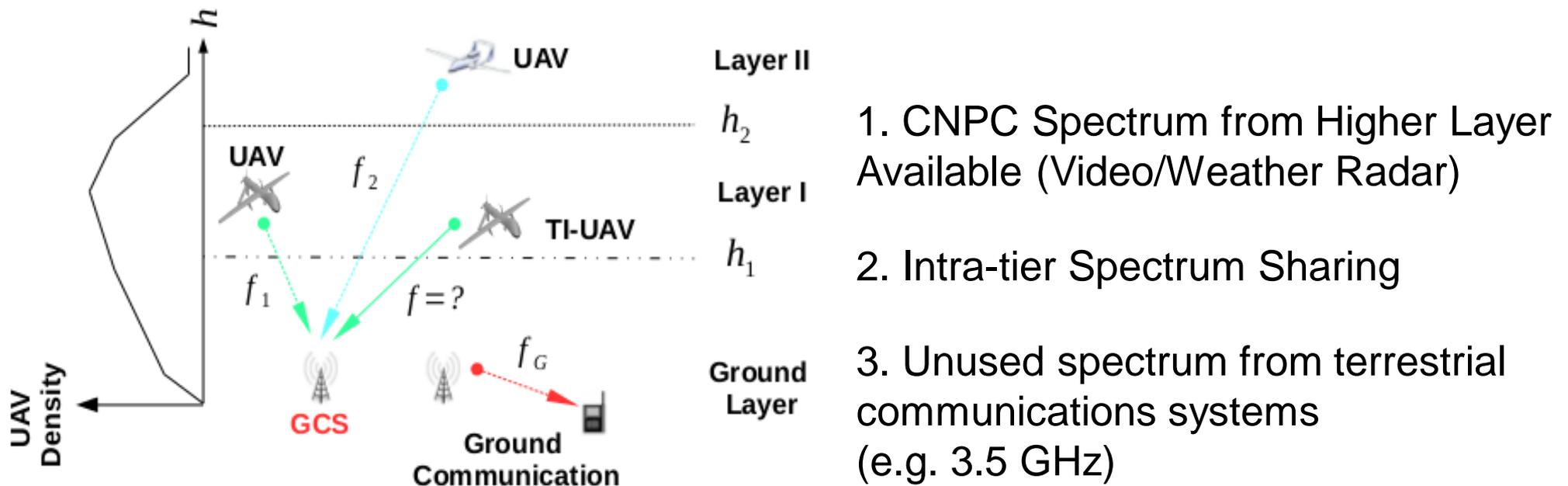


Radio LoS Probability



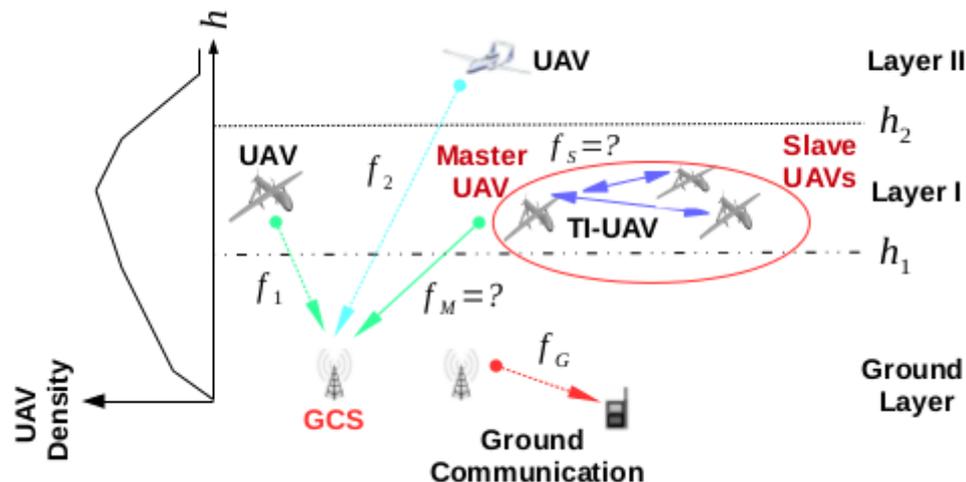
# DL Spectrum Sharing Scenarios

- UAV missions can be either of **individual** or **cooperative** nature
- Routes are either pre-planned (point-to-point or aerial-based) or unplanned



# DL Spectrum Sharing of Cooperative UAV Swarms

- Similar concepts apply for Cooperative UAV Swarms
- Choose the “best” Master UAV to optimize throughput [6]



# Conclusion

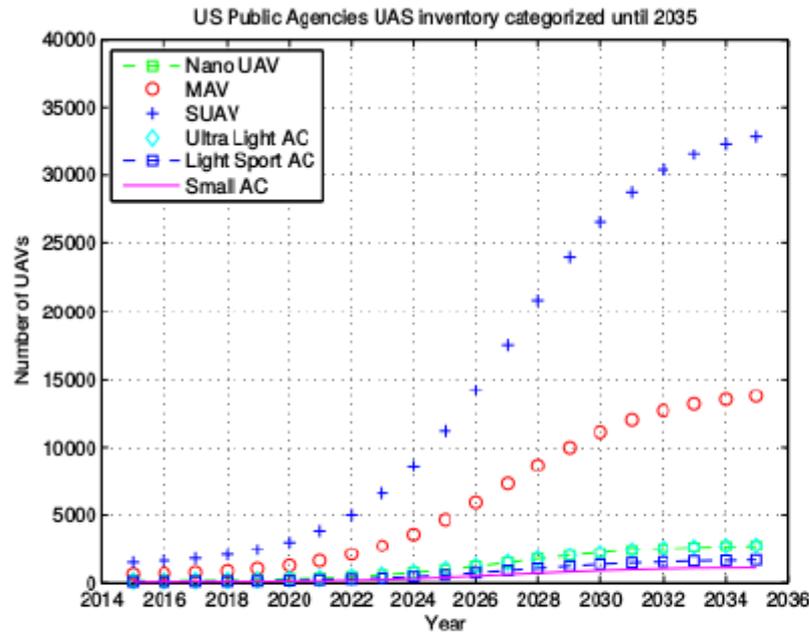
- Spectrum sharing solely based on sensing is not suitable for the UAS context
- Sensing as support of DSA
- Knowledge about neighboring UAVs (location, pre-determined route, phase of flight, etc.) needs to be available to make accurate decisions about opportunistic spectrum access
- A-priori knowledge of spectrum availability may also apply
- Location-based sensing allows the spectrum to “move”

# References

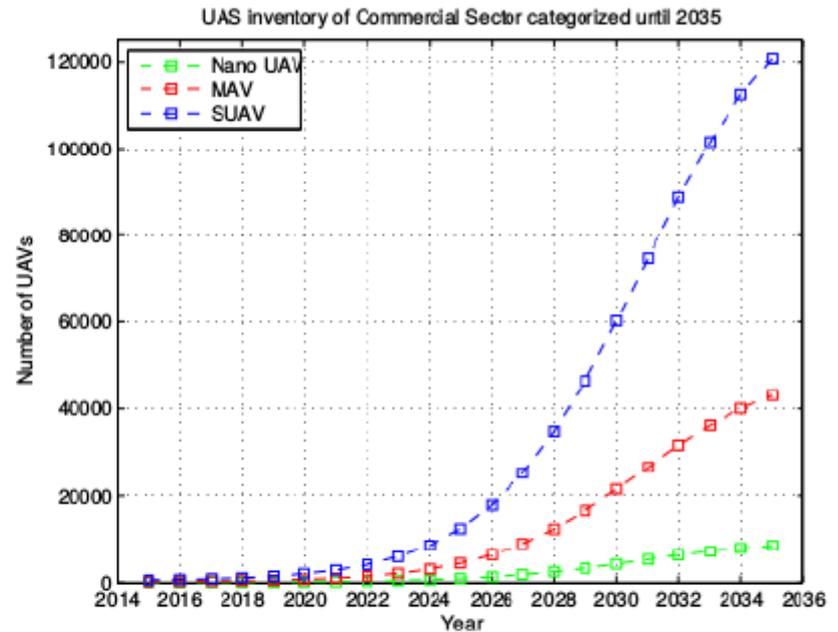
- [1] R. Austin, *Unmanned Aircraft Systems: UAVs Design, Development and Deployment*. Wiley, May 2010.
- [2] John A. Volpe National Transportation Systems Center, “Unmanned Aircraft System (UAS) Service Demand 2015 – 2035,” U.S. Department of Transportation, Tech. Rep. DOT-VNTSC-DoD-13-01, September 2013.
- [3] R. S. Stansbury, M. A. Vyas, and T. A. Wilson, “A Survey of UAS Technologies for Command, Control, and Communication (C3),” *Journal of Intelligent and Robotic Systems*, vol. 54, no. 1-3, pp. 61–78, 2009. [Online]. Available: <http://dblp.uni-trier.de/db/journals/jirs/jirs54.html#StansburyVW09>
- [4] ITU, “Characteristics of unmanned aircraft systems and spectrum requirements to support their safe operation in non-segregated airspace,” International Telecommunication Union, Tech. Rep. M.2171, December 2009.
- [5] A. Al-Hourani, S. Kandeepan, and A. Jamalipour, “Modeling Air-to-Ground Path Loss for Low Altitude Platforms in Urban Environments”, *Globecom* 2014.
- [6] I. Abualhaol and M. M. Matalgah, “Throughput optimization of cooperative uavs using adaptive channel assignment,” in *Wireless Communications and Networking Conference*, 2006. WCNC2006. IEEE, vol. 4, April 2006, pp. 2279–2284.

# Backup Slides

# Projected Absolute UAV Quantities



(a) Projection of public agency UAV quantities (without DoD)



(b) Projection of commercial UAV quantities

- Predicted Quantity for all 3 Type of Users by Function  $f(x) = p_1 + \frac{(p_2 - p_1)}{1 + 10^{p_4(p_3 - x)}}$

	$p_1$	$p_2$	$p_3$	$p_4$
Commercial	487.95	$2.03 \cdot 10^5$	15.75	0.18
Federal Agencies	207.22	$1.02 \cdot 10^4$	9.73	0.18
State and Local Agencies	$1.87 \cdot 10^3$	$4.64 \cdot 10^4$	12.49	0.19

# Link-Specific Data Rate Requirement

- CNPC Data Rate Requirement in bps [4]

	Flight Phase	Percentage Flight Phase	Command & Control				ATC Relay				S&A		
			Control		NavAID		ATC Voice		ATC Data		Target Track	Airborne Weather	Spare Time Video
			UL	DL	UL	DL	UL	DL	UL	DL	DL	DL	DL
Airport Surface and Low Altitude	Departure	42%	2,386	5,715	669	839	4,800	4,800	49	59	9,120	27,771	270,000
			=9,606				UL: =4,849 DL: =4,859						
	Arrival	58%	4,606	7,615	669	1,140	4,800	4,800	16	32	9,120	27,771	270,000
=14,030				UL: =4,816 DL: =4,832									
Average			0.42 · 9,606 + 0.58 · 14,030 =12,167				UL, DL ≈ 4,855				9,120	27,771	270,000
Medium and High Altitude	En-route	100%	1,201	2,356	669	839	4,800	4,800	23	28	9,120	3,968	27,000
			=5,062				UL: =4,823 DL: =4,828 UL, DL ≈ 4,855				9,120	3,968	27,000

# Cell Types

Cell Name	Configuration
A	<p>Diagram A shows a cylindrical cell with a diameter of 112 km and a height of 1,500 m. A central vertical cylinder has a diameter of 65 km. Two small square markers are located on the top surface of the main cylinder, one on each side of the central cylinder.</p>
B	<p>Diagram B shows a cylindrical cell with a diameter of 272 km and a height of 6,000 m. A central vertical cylinder has a diameter of 157 km. Two small square markers are located on the top surface of the main cylinder, one on each side of the central cylinder. The bottom surface is labeled "Surface".</p>
C	<p>Diagram C shows a cylindrical cell with a diameter of 545 km and a height of 14,000 m. A central vertical cylinder has a diameter of 315 km. Two small square markers are located on the top surface of the main cylinder, one on each side of the central cylinder. The bottom surface is labeled "Surface".</p>
D	<p>Diagram D shows a cylindrical cell with a diameter of 831 km and a height of 24,000 m. A central vertical cylinder has a diameter of 480 km. Two small square markers are located on the top surface of the main cylinder, one on each side of the central cylinder. The bottom surface is labeled "Surface".</p>

# LAP ATG Propagation

